

$$\begin{aligned} \text{Chapter 3} & \quad e^{st} \rightarrow H(s) e^{st} \\ \text{FS} & \quad z^n \rightarrow H(z) z^n \\ H(s) & = \int_{-\infty}^{+\infty} h(t) e^{-st} dt \\ H(z) & = \sum_{k=0}^{\infty} h[k] z^{-k} \\ S=jw, Z=e^{jw} & \end{aligned}$$

$$\begin{aligned} \cdot \phi_k(t) &= e^{jkw_0 t}, \text{谐波关系} \\ \cdot \text{若 } x(t) \text{ 为实信号, 则: } (x^*(t)) &= x(t) \\ x(t) &= a_0 + 2 \sum_{k=1}^{\infty} A_k \cos(kw_0 t + \theta_k) \\ \star A_n &= \frac{1}{T} \int_0^T x(t) e^{-jn w_0 t} dt \\ \boxed{X_n = \sum_k a_k e^{jk w_0 t}} & \end{aligned}$$

- 收敛条件: ① T 内能量有限

$$\textcircled{2} \int_T |x(t)| dt < \infty, \int_T |x'(t)| dt < \infty$$

③ T 内有限个 max, min

④ 有限时间内, 只含有有限个连续点

$$\cdot \text{性质: } \boxed{x(t-t_0) \xrightarrow{\text{FS}} e^{-jkw_0 t_0} x(t)}$$

$$x(t) \xrightarrow{\text{FS}} A_k$$

$$x(at) \xrightarrow{\text{FS}} A_k \text{ (但基波频率变)} \downarrow$$

$$x(t)y(t) \xrightarrow{\text{FS}} \sum_{l=-\infty}^{\infty} a_l b_{l-k}$$

$$\boxed{\int_T x(t)y(t) dt \xrightarrow{\text{FS}} T a_k b_k}$$

$$x^*(t) \xrightarrow{\text{FS}} A_k^* e^{jkw_0 t}$$

$$\frac{dx(t)}{dt} \xrightarrow{\text{FS}} jkw_0 A_k, A_{k-M}$$

$$\boxed{\int_{-\infty}^t x(t) dt \xrightarrow{\text{FS}} \frac{1}{jkw_0} A_k}$$

π(t) 实偶, A_k 实偶;

π(t) 实奇, A_k 纯虚奇

$$\frac{1}{T} \int_T |x(t)|^2 dt = \sum_{k=0}^{\infty} |A_k|^2$$

$$\Delta |x(t)|^2 = x(t) \cdot x^*(t)$$

Δ 方波 FS (T, T_1).

$$A_k = \frac{\sin(kw_0 T_1)}{k\pi}$$

$$A_0 = -\frac{2T_1}{T} \uparrow \text{离散}$$

$$\star A_k = \frac{1}{N} \sum_{n=0}^{N-1} x[n] e^{-jknw_0}$$

$$x[n] = \sum_{k=0}^{N-1} A_k e^{jk w_0 n}$$

$$A_k = A_{k+N}$$

Δ 方波 FS (N_1, N).

$$A_k = \frac{1}{N} \frac{\sin[(k\pi)(N_1+1/2)]}{\sin(k\pi/N)}$$

$$A_0 = \frac{2N+1}{N}$$

· 性质(与连续不同)

$$x[m] = \begin{cases} x[n/m], m/n \\ 0, m/n \end{cases}$$

$$\xrightarrow{\text{FS}} \frac{1}{m} A_k$$

$$x[n]y[n] \xrightarrow{\text{FS}} \sum_{l=-\infty}^{\infty} a_l b_{l-k}$$

(Δ: 两个周期上)

$$x[n] - x[n-1] \leftrightarrow (1 - e^{-jkw_0}) A_k$$

$$\sum_{k=-\infty}^{\infty} X[k] \leftrightarrow (1 - e^{-jkw_0}) A_k$$

(仅 A_0 = 0 时, 才有有限值且为周期的)

$$\begin{aligned} \frac{1}{N} \sum_{n=0}^{N-1} |x[n]|^2 &= \sum_{k \leq N-1} |A_k|^2 \\ \cdot \text{FS \& LTI} & \\ H(jw) &= \int_{-\infty}^{+\infty} h(t) e^{-jwt} dt \quad \boxed{5} \\ H(e^{jw}) &= \sum_{n=0}^{+\infty} h[n] e^{-jwn} \\ y(t) &= \sum_{k=-\infty}^{+\infty} A_k H_k w_0 e^{jkw_0 t} \\ Y[n] &= \sum_{k=-\infty}^{N-1} A_k H_k e^{jk w_0 n} \end{aligned}$$

$$\boxed{\text{Chapter 4 FT}}$$

$$x(t) = \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(jw) e^{jw t} dw$$

$$X(jw) = \int_{-\infty}^{+\infty} x(t) e^{-jw t} dt$$

FT收敛条件: ↑

周期的FT: ↑

$$\Delta X(jw) = \sum_{k=-\infty}^{+\infty} 2\pi A_k \delta(w - kw_0)$$

$$x(t) = \sum_{k=-\infty}^{+\infty} A_k e^{jk w_0 t}$$

· 性质: $x(t-t_0) \xrightarrow{F} e^{-jw_0 t_0} X(jw)$

$$e^{jw_0 t} x(t) \xrightarrow{F} X(j(w-w_0))$$

$$x^*(t) \xrightarrow{F} X^*(-jw)$$

$$x(t) \xrightarrow{F} X(-jw)$$

$$x(at) \xrightarrow{F} \frac{1}{|a|} X(\frac{jw}{a})$$

$$x(t)y(t) \xrightarrow{F} X(jw)Y(jw)$$

$$x(t)y(t)x \xrightarrow{F} \frac{1}{2\pi} \int_{-\infty}^{+\infty} X(j\theta) Y(j(w-\theta)) d\theta$$

$$\frac{dX(jw)}{dt} \xrightarrow{F} jw X(jw)$$

$$x(t) \xrightarrow{F} j \frac{dX(jw)}{dw}$$

$$x_e(t) \Rightarrow \text{Re} X(jw)$$

$$x_o(t) \Rightarrow j \text{Im} X(jw)$$

对偶性质

$$\int_{-\infty}^{+\infty} |x(t)|^2 dt = \frac{1}{2\pi} \int_{-\infty}^{+\infty} |X(jw)|^2 dw$$

· 解系统:

$$\sum_{k=0}^N A_k \frac{d^k y(t)}{dt^k} = \sum_{k=0}^M B_k \frac{d^k x(t)}{dt^k}$$

$$\boxed{y(t) H(jw) = \sum_{k=0}^M b_k c_k w^k}$$

★ 基本FT对:

$$F\{e^{jk w_0 t}\} = \pi \delta(w - kw_0)$$

$$\boxed{F\{1\} = 2\pi \delta(w)}$$

$$x(t) = \begin{cases} 1, 0 < t < T_1 \\ 0, T_1 < t < T_2 \end{cases}$$

$$x(t+T) = x(t), \forall T$$

$$F\{x(t)\} = \frac{2\pi}{T} \sum_{k=-\infty}^{+\infty} \delta(w - \frac{2\pi k}{T})$$

$$x(t) = \begin{cases} 1, 0 < t < T \\ 0, t > T \end{cases} F\{x(t)\} = \frac{2\pi \sin(wT)}{w}$$

$$F\{\delta(t)\} = 1$$

$$F\{\text{rect}(t)\} = \frac{1}{jw} + \pi \delta(w)$$

$$F\{\delta(t-t_0)\} = e^{-jw t_0}$$

$$\begin{aligned} F\{e^{-at} x(t)\} &= \frac{1}{a+jw} \\ F\{te^{-at} x(t)\} &= \frac{1}{(a+jw)^2} \\ F\{\frac{t^{-1}}{(n-1)!} e^{-at} x(t)\} &= \frac{1}{(a+jw)^n} \\ F\{e^{-at}\} &= \frac{1}{a+jw}, (a > 0) \end{aligned}$$

$$\boxed{\text{Chapter 1}}$$

$$E = \int_{t_1}^{t_2} |x(t)|^2 dt, P = \frac{E}{t_2 - t_1}$$

$$E = \sum_{n=1}^{\infty} |X[n]|^2, \text{看}$$

$$P = E/(n_2 - n_1 + 1)$$

$$E_0 = \int_{-\infty}^{+\infty} |x(t)|^2 dt, \text{连}$$

$$P_0 = \lim_{T \rightarrow \infty} \frac{1}{2T} \int_{-T}^T |x(t)|^2 dt$$

$$E_0 = \sum_{n=-\infty}^{\infty} |X[n]|^2,$$

$$P_0 = \lim_{N \rightarrow \infty} \frac{1}{N+1} \sum_{n=-N}^N |X[n]|^2$$

$$F-E: E_0 < \infty F-P: P_0 < \infty$$

$$I-E/P: P_0, E_0 \quad E_0 = \infty$$

$$x(t+\beta), \text{拉伸} \rightarrow x, \text{shift} \rightarrow \beta$$

$$\text{Expo Sign: } c e^{at}, c=1$$

$$a \text{ 仅有虚部, } T_0 = \frac{2\pi}{|w_0|}$$

$$\text{Sinu Signal: } \text{Acos}(w_0 t + \phi)$$

$$T_0 = \frac{2\pi}{w_0}, \text{两信号的 F-P:}$$

$$P_{\text{expo}} = \frac{1}{T_0} \int_{-T_0}^{T_0} |e^{jw_0 t}|^2 dt = 1$$

$$P_{\text{sinu}} = \frac{1}{T_0} \int_{-T_0}^{T_0} |\text{Re}[e^{jw_0 t}]|^2 dt$$

$$\text{Oscillation Rate: } \frac{1}{2}$$

$$\text{Expo: } \text{out} \pi, \text{w}, \text{rate} \uparrow$$

$$\text{Pi} \sim 2\pi, \text{w} \uparrow, \text{rate} \uparrow$$

$$\text{Sinu: } \text{out} \pi, \text{w}, \text{rate} \uparrow$$

$$\text{Pi} \sim 2\pi, \text{w} \downarrow, \text{rate} \uparrow$$

$$\text{离散信号周期: } N = 2\pi M, M = \frac{2\pi}{w_0}$$

$$\Delta x[n] = x[n] - x[n-1]$$

$$\delta(t) = dx(t)/dt$$

$$\uparrow \text{集中面积集中}$$

$$\rightarrow t \rightarrow t=0$$

$$x(t) = x(t+1) \Rightarrow x(t) = 2x(t)$$

$$\text{System Property: current Memoryless: } \text{输出只与输入有关}$$

$$\text{Invertible: 不同输入不同输出}$$

$$\text{Causality: 输出只与过去输入}$$

$$\text{Stability: bounded in} \rightarrow \text{bounded out}$$

$$\rightarrow y[n-n_0]$$

$$\Delta: y[n] = y[n-n_0], n > 0, \text{非!}$$

$$\text{则不 causal}$$

$$\text{II: 微/差分, II: 相加}$$

$$\text{III: 积分, III: 对偶}$$

Chapter 2

SIN 通过 LTI 系统 output 记作 h[n]

$$x[k] \delta[n-k] \rightarrow LTI \rightarrow h[k] \delta[n-k]$$

$$\sum_{k=-\infty}^{+\infty} x[k] h[n-k] = x[n] * h[n]$$

$$\cdot x[n] \rightarrow h[n-m] \rightarrow y[n-m] \rightarrow !$$

$$y(t) = \int_{-\infty}^{+\infty} x(\tau) h(t-\tau) d\tau \quad \text{out} \rightarrow h[n-m]$$

$$\cdot \text{Properties: } \boxed{3} \uparrow \boxed{4} \downarrow$$

$$\textcircled{1} \text{交换: } x(t) * h(t) = h(t) * x(t)$$

$$\textcircled{2} \text{分配: } \boxed{3} \uparrow \boxed{4} \downarrow$$

$$\textcircled{4} \text{无记忆: } n \neq 0, h[n] = 0; h(t) = 0, t \neq 0.$$

$$\textcircled{5} \text{可逆性: } h(t) * h(t) = \delta(t)$$

$$E[h[n]] = u[n], \delta[n] = u[n] - u[n-1]$$

$$= u[n] * [\delta[n] - \delta[n-1]], \therefore h[n] = \delta[n] - \delta[n-1]$$

$$\textcircled{6} \text{因果性: } h[0]=0, t<0; h(t)=0, t>0$$

$$\Delta: \text{初始松弛条件: 在某时刻前 input} \neq 0, \text{则 output 也应为 0.}$$

$$\textcircled{7} \text{稳定性: } \sum_{k=-\infty}^{+\infty} |h[k]| < 0, \int_{-\infty}^{+\infty} |h(t)| dt < \infty$$

$$\text{Unit Step Response: } \boxed{1} \uparrow \boxed{2} \downarrow$$

$$SIN/S(t) \rightarrow x[n] = u[n]/(u[n] - u[n-1]) \text{ 时向}$$

$$SIN-S[n-1] = h[n], S[n] = \sum_{k=-\infty}^n h[k]$$

$$h(t) = S'(t), s(t) = \int_{-\infty}^t h(t') dt$$

$$\text{特解: 设与 } x(t) \text{ 同形式; 齐次解: } A e^{st}$$

$$\text{初值松驰: } y(0) = 0$$

$$\sum_{k=0}^N A_k \frac{d^k y(t)}{dt^k} = \sum_{k=0}^M B_k \frac{d^k x(t)}{dt^k} \quad \boxed{16}$$

$$\text{则初值: } y=0, t \leq t_0, y(t_0) = \dots = \frac{d^N y(t_0)}{dt^N} = Q$$

$$\boxed{1} \text{ FS 对 (连续)}$$

$$\boxed{2} \text{ FS 性质 (连续)}$$

$$\boxed{3} \text{ FS 对 (离散)}$$

$$\boxed{4} \text{ FS 性质 (离散)}$$

$$\boxed{5} \text{ FS \& LTI (} x[n] \text{, } H(jw) \Rightarrow y[n] \text{)}$$

$$\boxed{6} \text{ FT 对 } \boxed{7} \text{ } X(jw) \& A_k \text{ 关系}$$

$$\boxed{8} \text{ FT 性质 } \boxed{9} \text{ 解系统}$$

$$\boxed{10} \text{ 基本 FT 对 } \boxed{11} \text{ } S[n].u[n]$$

$$\boxed{12} \text{ system 性质 } \boxed{13} \text{ 卷积}$$

$$\boxed{14} \text{ 卷积性质 (} \boxed{15} \text{ Unit Step Response). }$$

$$\boxed{16} \text{ 解微差分方程}$$

$$\text{Duality: } x_1(t) \rightarrow x_2(jw) = \bar{x}_1(w)$$

$$x_2(t) = F^{-1}\{x_1(w)\}, x_1(t) \text{ 中 } t = -t,$$

$$\text{然后 } t, w \text{ 名义 对偶}$$



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